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Seismic Motions
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Modeling and Simulation of Static and Dynamic Behavior of Soil Structure Systems

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Denver, August. 2018

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Motivation

Improve modeling and simulation for infrastructure objects

Use select fidelity (high ↔ low) numerical models to analyze static and dynamic behavior of soil/rock structure fluid systems

Reduction of modeling uncertainty, ability to perform desired level of sophistication modeling and simulation

Accurately follow the flow of input and dissipation of energy in a soil structure system

Development of an expert system for modeling and simulation of Earthquakes, Soils, Structures and their Interaction, MS-ESSI: <http://ms-essi.info/>

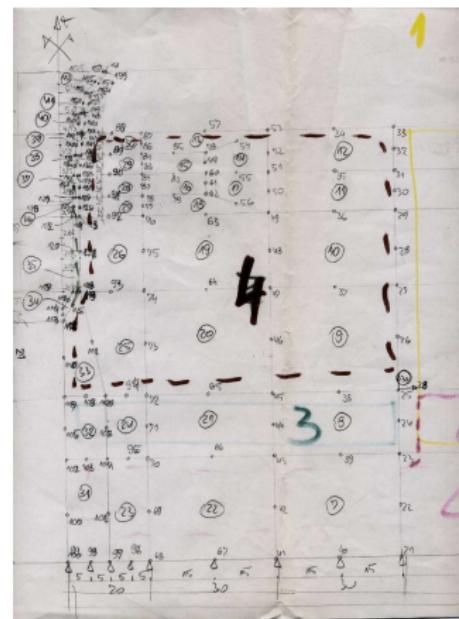
Predictive Capabilities

- ▶ Prediction under Uncertainty: use of computational model to predict the state of SSI system under conditions for which the computational model has not been validated.
- ▶ Verification provides evidence that the model is solved correctly. Mathematics issue.
- ▶ Validation provides evidence that the correct model is solved. Physics issue.
- ▶ Modeling and parametric uncertainties are always present, need to be addressed
- ▶ Goal: Predict and Inform rather than (force) Fit

Motivation: Modeling Uncertainty

- ▶ Simplified modeling: Features (important ?) are neglected, simplified out (6C ground motions, inelasticity)
- ▶ Modeling Uncertainty: unrealistic (unnecessary?) modeling simplifications
- ▶ Chief Engineer in my old company: "I would really love to know what would a realistic response this object be"

Spillway Dynamic Analysis, '88-'89



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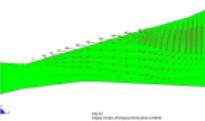
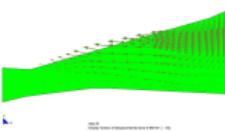
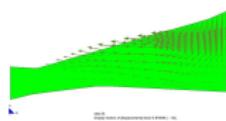
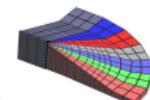
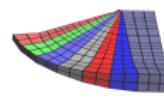
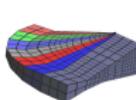
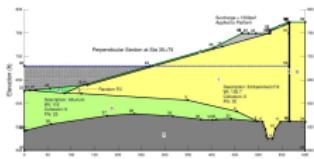
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Behkme Dam Project, Iraq, '89-'90



Wolf Creek Dam, '09-'10



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MS-ESSI Simulator System

The MS-ESSI, Realistic Modeling and Simulation of Earthquakes, Soils, Structures and their Interaction. Simulator is a software, hardware and documentation system for high fidelity, high performance, time domain, nonlinear/inelastic, deterministic or probabilistic, 3D, finite element modeling and simulation of:

- ▶ statics and dynamics of soil,
- ▶ statics and dynamics of rock,
- ▶ statics and dynamics of structures,
- ▶ statics of soil-structure systems, and
- ▶ dynamics of earthquake-soil-structure system interaction

MS-ESSI Simulator System

- ▶ MS-ESSI System Components
 - ▶ MS-ESSI Pre-processor (gmsh/gmESSI, X2ESSI)
 - ▶ MS-ESSI Program (local, remote, cloud)
 - ▶ MS-ESSI Post-Processor (Paraview, Python, Matlab)
- ▶ MS-ESSI System availability:
 - ▶ Educational Institutions: Amazon Web Services (AWS), free
 - ▶ Government Agencies, National Labs: AWS GovCloud
 - ▶ Professional Practice: AWS, commercial
- ▶ MS-ESSI Short Courses (online, this Fall)
- ▶ System description and documentation at
<http://ms-essi.info/>

Quality Assurance

- ▶ Full verification suit for each element, model, algorithm
- ▶ Certification process in progress for NQA-1 and ISO-90003-2014

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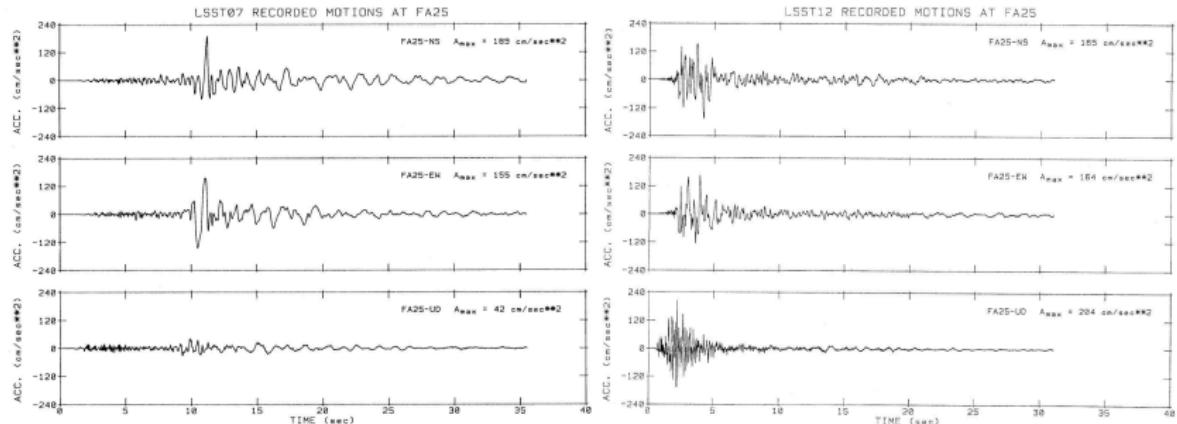
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3D (6D) Seismic Motions

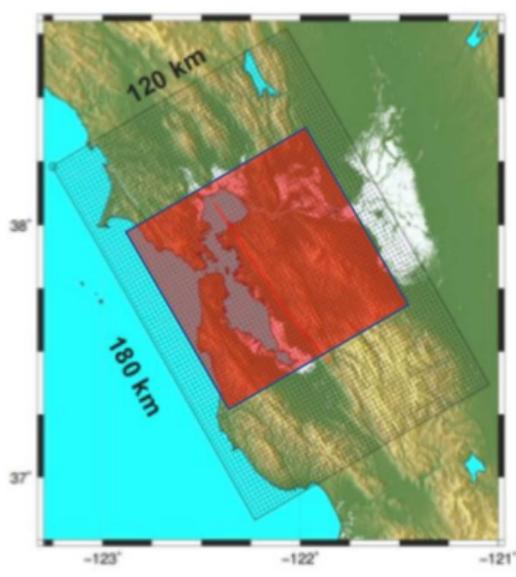
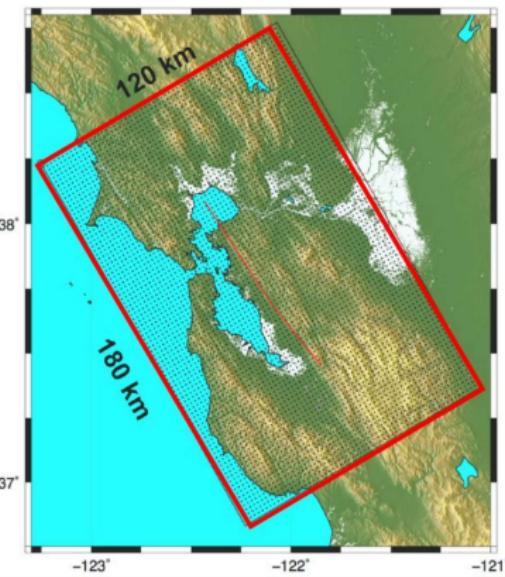
- ▶ All (most) measured motions are full 3D (6D)
- ▶ One example of an almost 2D motion (LSST07, LSST12)



Regional Geophysical Models

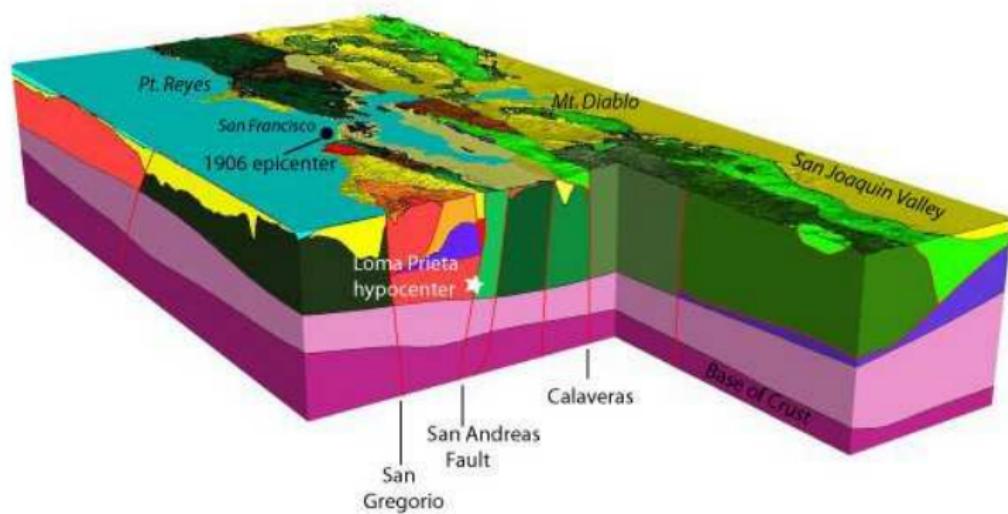
- ▶ Free Field seismic motions on regional scale
- ▶ Knowledge of geology (deep and shallow) needed
- ▶ Developed using SW4 and/or MS-ESSI
- ▶ Collaboration with LLNL: Dr. Rodgers, Dr. Pitarka and Dr. Petersson

Regional Geophysical Models



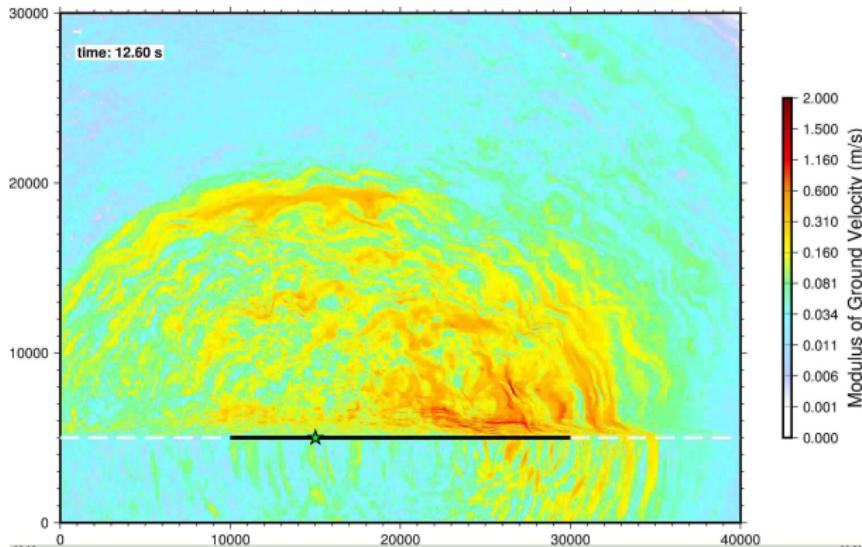
Rodgers and Pitarka

Regional Geophysical Models



USGS

Example Regional Model (Rodgers)

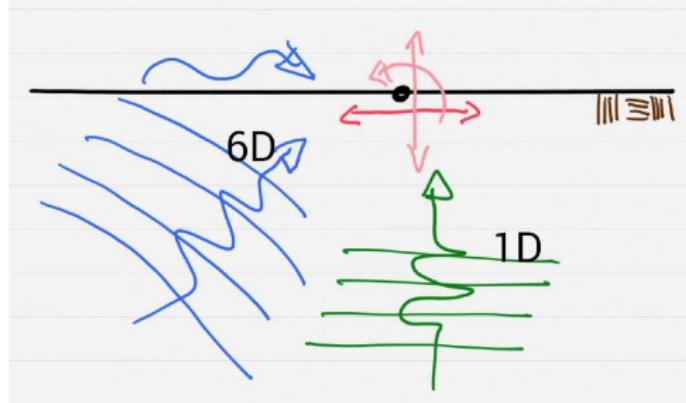


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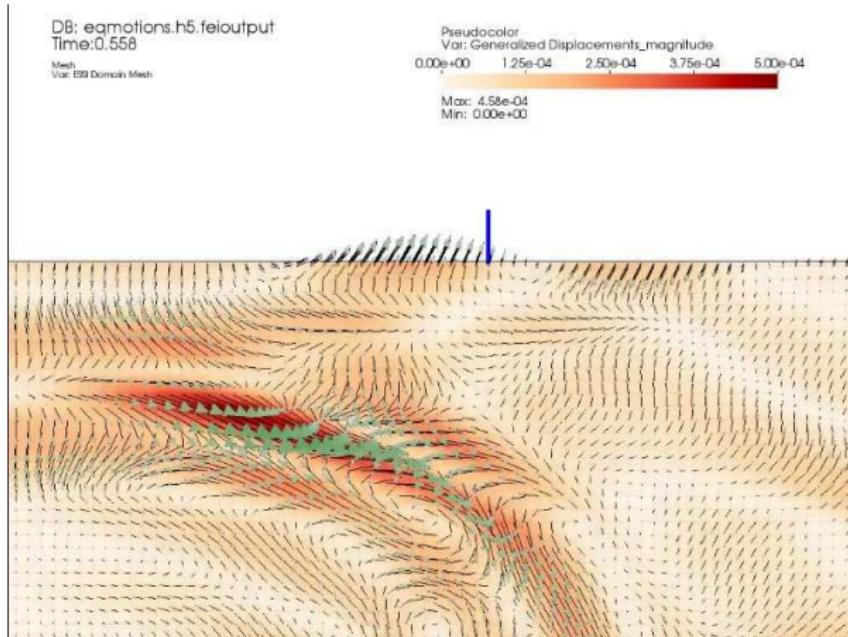
Regional Models

ESSI: 6C or 1C Seismic Motions

- ▶ Assume that a full 6C (3C) motions at the surface are only recorded in one horizontal direction
- ▶ From such recorded motions one can develop a vertically propagating shear wave (1C) in 1D
- ▶ Apply such vertically propagating shear wave to same soil-structure system



6C Free Field Motions (closeup)



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Jeremić et al.

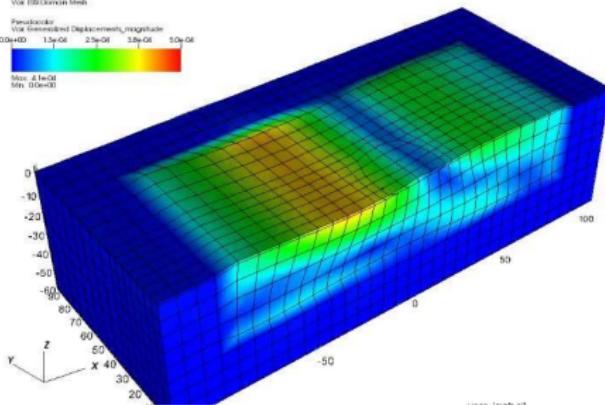
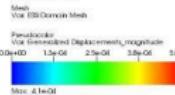
MS-ESSI

Regional Models

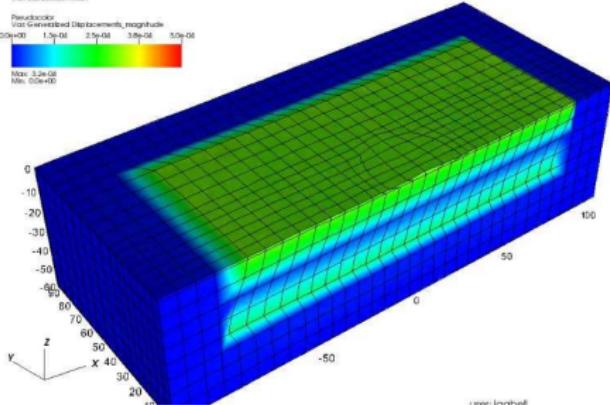
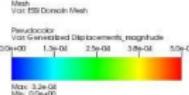
1C vs 6C Free Field Motions

- ▶ One component of motions (1D) from 3D
- ▶ Excellent fit

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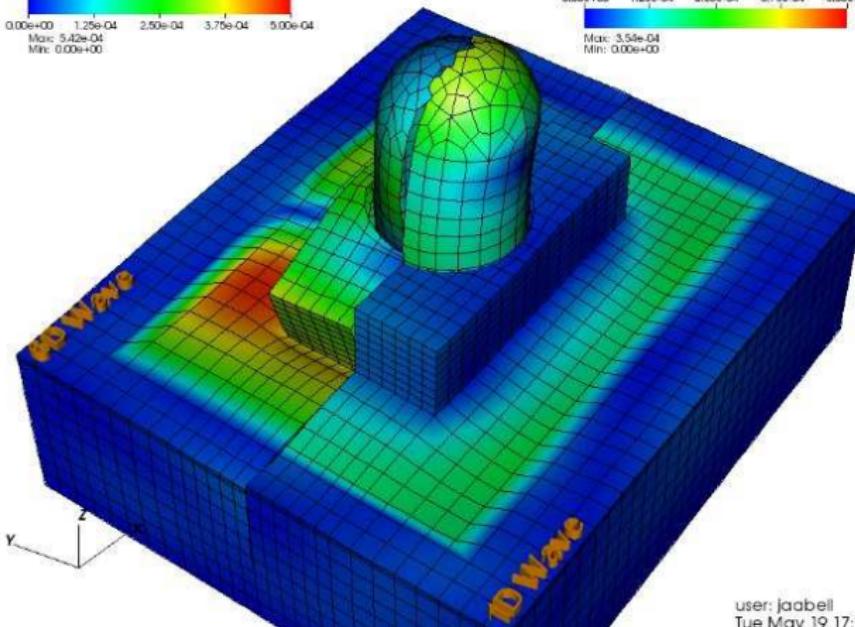
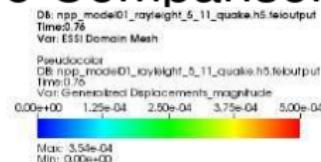
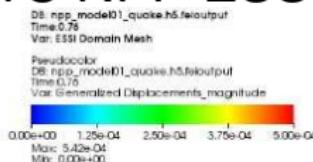


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6C vs 1C NPP ESSI Response Comparison



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Stress Test Motions

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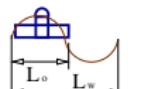
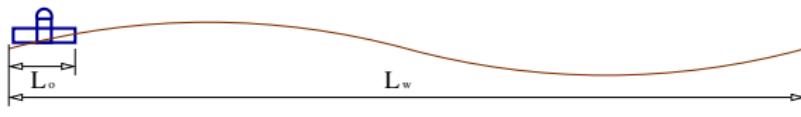
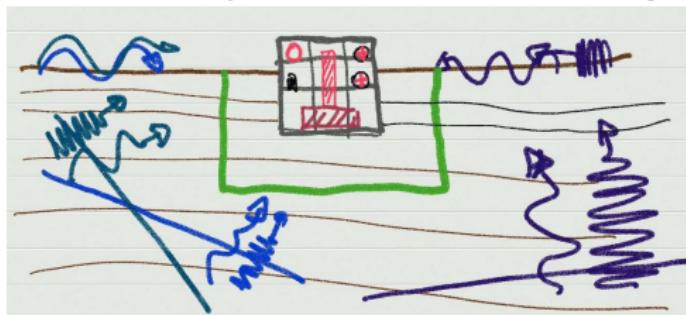
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Stress Test Motions

Stress Testing SSI Systems

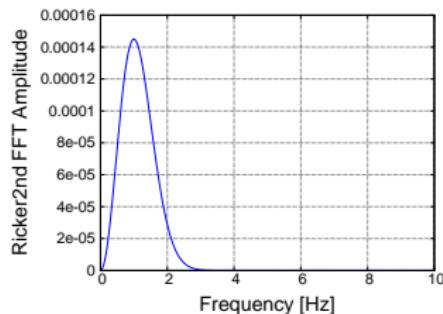
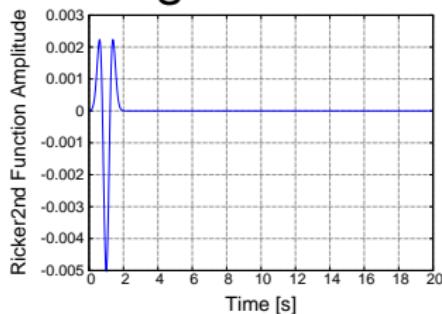
- ▶ Excite SSI system with a suite of seismic motions
- ▶ Waves: P, SV, Sh, Surface (Rayleigh, Love, etc.)
- ▶ Variation in inclination, frequency, energy and duration
- ▶ Try to "break" the system, shake-out strong and weak links



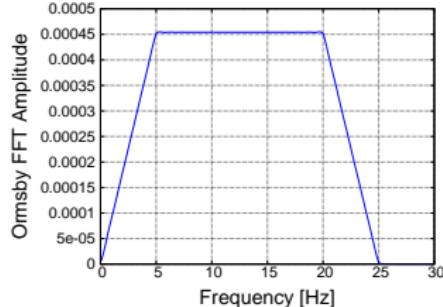
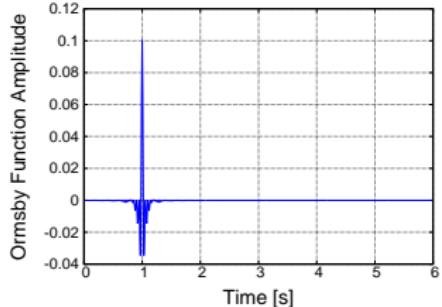
Stress Test Motions

Stress Test Source Signals

► Ricker



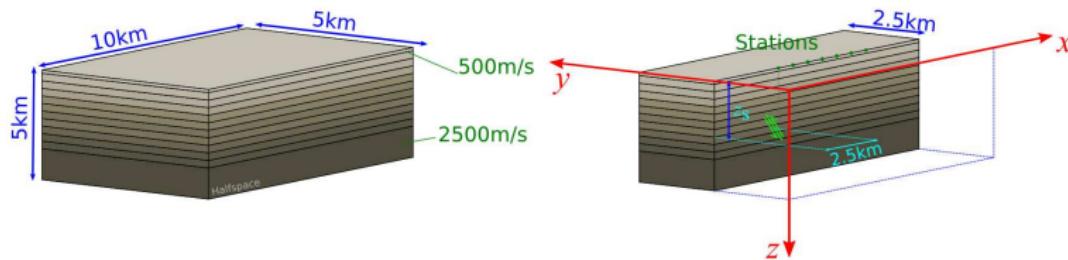
► Ormsby



Stress Test Motions

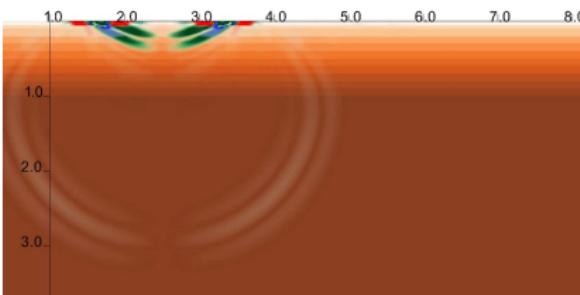
Layered Soil Models

- ▶ Point source location matrix
- ▶ Plane waves matrix (Thomson and Haskell solution)

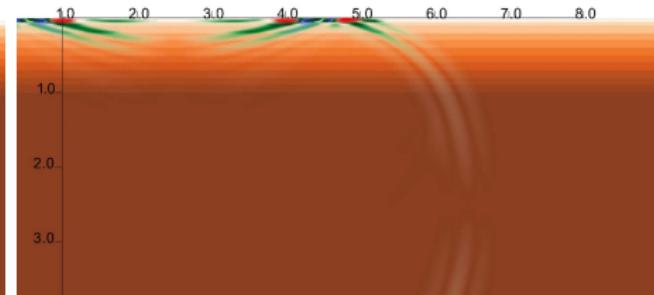


Stress Test Motions

Layered System, Variable Source Depth



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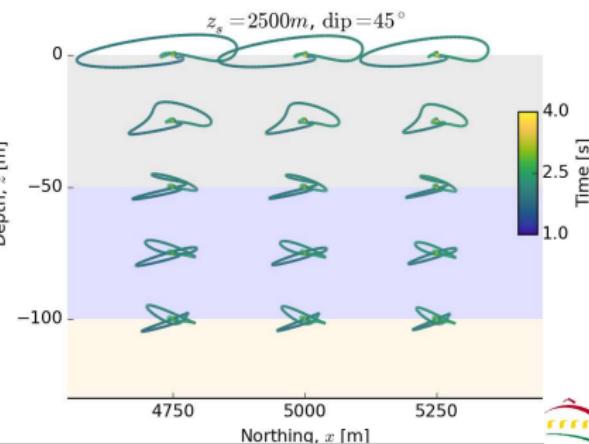
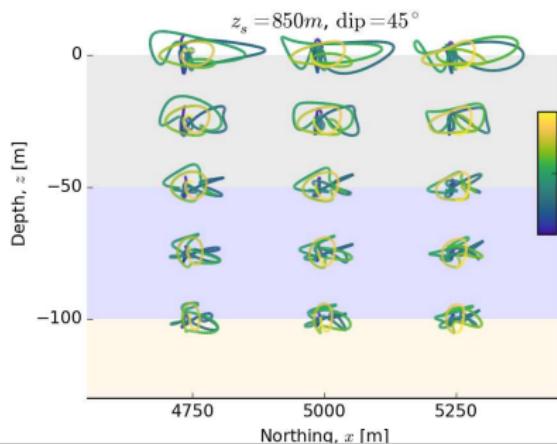
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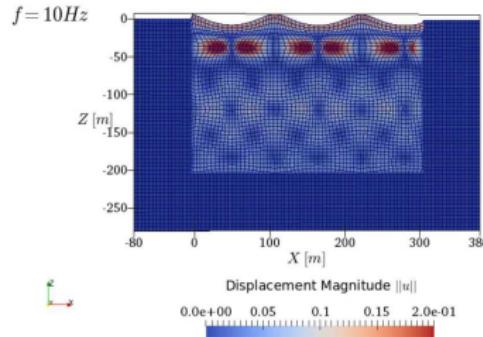
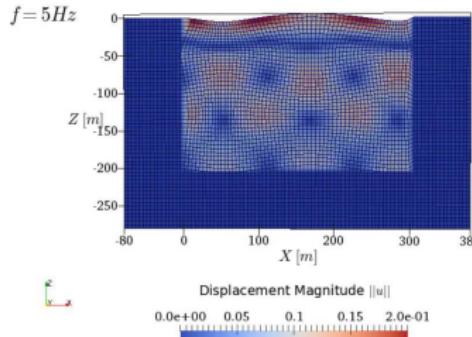
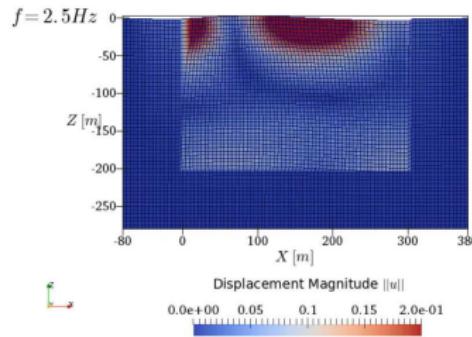
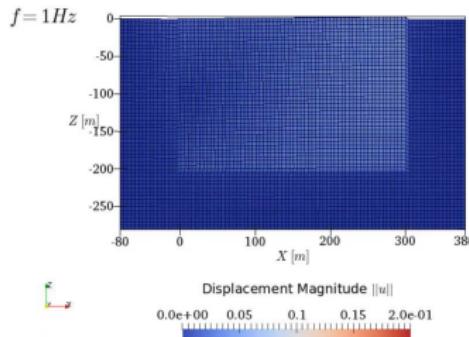
Stress Test Motions

Layered System, Displacement Traces

- ▶ Epicenter is 2500m away from the location of interest
- ▶ Source depth 850m (left) and 2500m (right)
- ▶ Different wave propagation path to the point of interest
- ▶ Surface waves quite pronounced
- ▶ Layered geology did not filter out surface waves

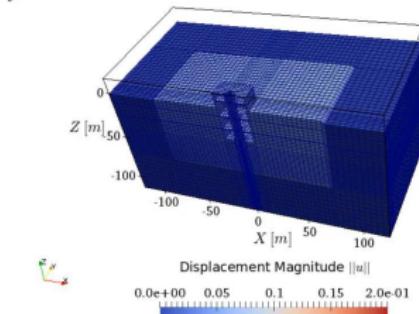
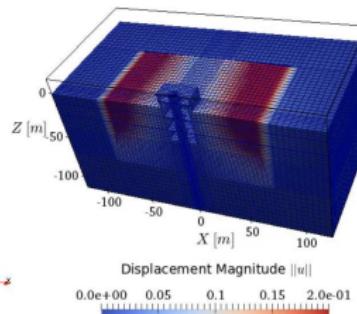
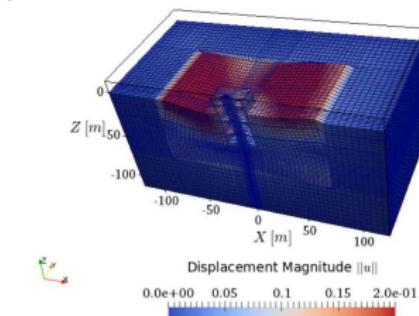
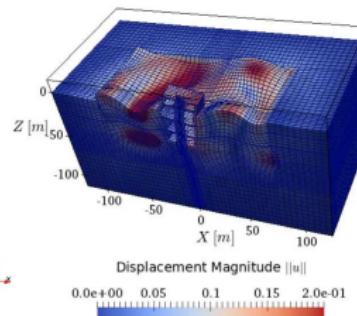


Stress Test Motions

Free Field, Variation in Input Frequency, $\theta = 60^\circ$ 

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Stress Test Motions

SMR ESSI, Variation in Input Frequency, $\theta = 60^\circ$ $f = 1\text{Hz}$  $f = 2.5\text{Hz}$  $f = 5\text{Hz}$  $f = 10\text{Hz}$ 

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Energy Input and Dissipation

Energy input, dynamic forcing

Energy dissipation outside SSI domain:

SSI system oscillation radiation

Reflected wave radiation

Energy dissipation/conversion inside SSI domain:

Inelasticity of soil, contact zone, structure, foundation, dissipators

Viscous coupling with internal/pore fluids, and external fluids

Numerical energy dissipation/production

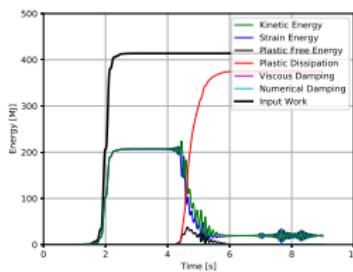
Fully Coupled Formulation, u-p-U

$$\begin{bmatrix} (M_s)_{KijL} & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & (M_f)_{KijL} \end{bmatrix} \begin{bmatrix} \ddot{\bar{U}}_{Lj} \\ \ddot{\bar{p}}_N \\ \ddot{\bar{U}}_{Lj} \end{bmatrix} + \begin{bmatrix} (C_1)_{KijL} & 0 & -(C_2)_{KijL} \\ 0 & 0 & 0 \\ -(C_2)_{LjiK} & 0 & (C_3)_{KijL} \end{bmatrix} \begin{bmatrix} \dot{\bar{U}}_{Lj} \\ \dot{\bar{p}}_N \\ \dot{\bar{U}}_{Lj} \end{bmatrix} \\
 + \begin{bmatrix} (K^{EP})_{KijL} & -(G_1)_{KiM} & 0 \\ -(G_1)_{LjM} & -P_{MN} & -(G_2)_{LjM} \\ 0 & -(G_2)_{KiL} & 0 \end{bmatrix} \begin{bmatrix} \bar{U}_{Lj} \\ \bar{p}_M \\ \bar{U}_{Lj} \end{bmatrix} = \begin{bmatrix} \bar{f}_{Ki}^{\text{solid}} \\ 0 \\ \bar{f}_{Ki}^{\text{fluid}} \end{bmatrix}$$

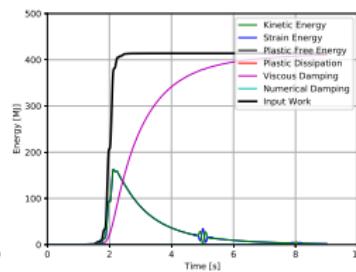
Fully Coupled Formulation, u-p-U

$$\begin{aligned}
 (M_s)_{KijL} &= \int_{\Omega} H_K^u (1-n) \rho_s \delta_{ij} H_L^u d\Omega & (M_f)_{KijL} &= \int_{\Omega} H_K^u n \rho_f \delta_{ij} H_L^u d\Omega \\
 (C_1)_{KijL} &= \int_{\Omega} H_K^u n^2 k_{ij}^{-1} H_L^u d\Omega & (C_2)_{KijL} &= \int_{\Omega} H_K^u n^2 k_{ij}^{-1} H_L^u d\Omega \\
 (C_3)_{KijL} &= \int_{\Omega} H_K^u n^2 k_{ij}^{-1} H_L^u d\Omega & (K^{EP})_{KijL} &= \int_{\Omega} H_{K,m}^u D_{imjn} H_{L,n}^u d\Omega \\
 (G_1)_{KiM} &= \int_{\Omega} H_{K,i}^u (\alpha - n) H_M^p d\Omega & (G_2)_{KiM} &= \int_{\Omega} n H_{K,i}^u H_M^p d\Omega \\
 P_{NM} &= \int_{\Omega} H_N^p \frac{1}{Q} H_M^p d\Omega
 \end{aligned}$$

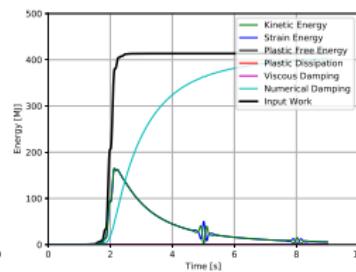
Energy Dissipation Control Mechanisms



Plasticity



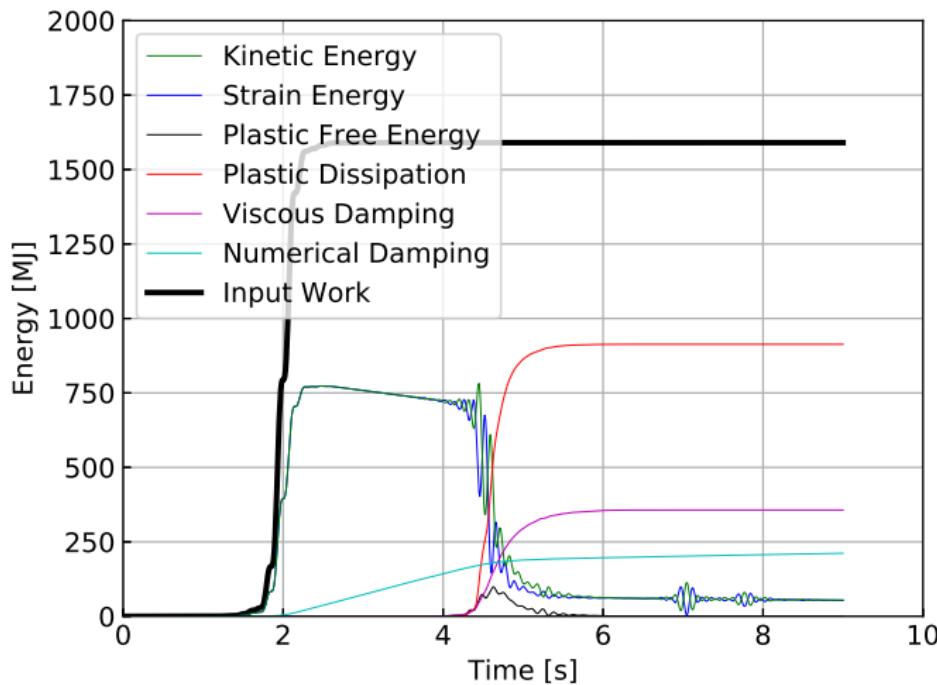
Viscous



Numerical

Energy Dissipation

Energy Dissipation Control



Energy Dissipation

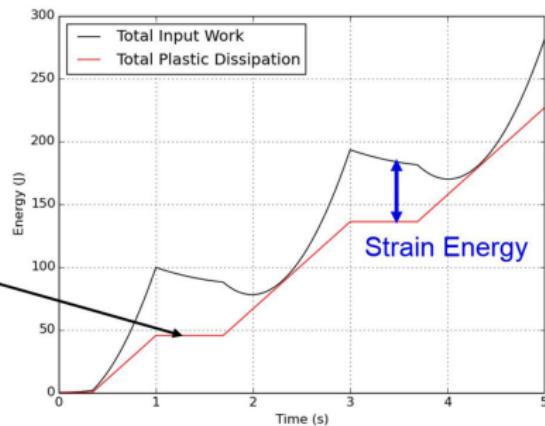
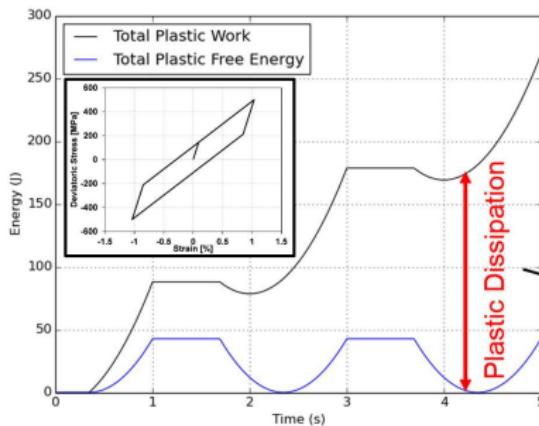
Energy Dissipation on Material Level

Single elastic-plastic element under cyclic shear loading

Difference between plastic work and plastic dissipation

Plastic work can decrease

Plastic dissipation always increases

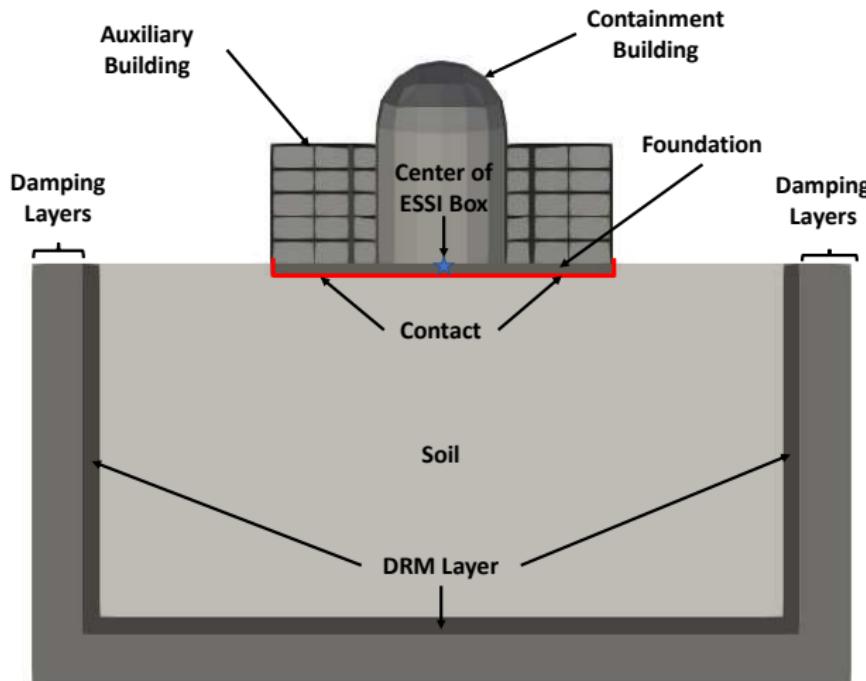


Inelastic Modeling for NPP and Components

- ▶ Soil elastic-plastic
 - ▶ Dry, single phase
 - ▶ Unsaturated (partially saturated)
 - ▶ Fully saturated
- ▶ Contact, inelastic, soil/rock – foundation
 - ▶ Dry, single phase, Normal (hard and soft, gap open/close), Friction (nonlinear)
 - ▶ Fully saturated, suction and excess pressure (buoyant force)
- ▶ Structural inelasticity/damage
 - ▶ Nonlinear/inelastic 1D reinforced concrete fiber beam
 - ▶ Nonlinear/inelastic 2D reinforced concrete element
 - ▶ Alcali Silica Reaction concrete modeling

Energy Dissipation

NPP Model

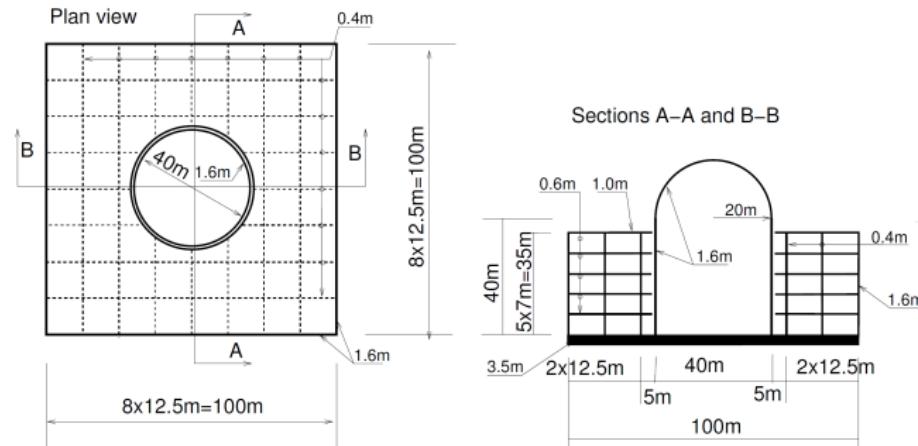


Energy Dissipation

Structure Model

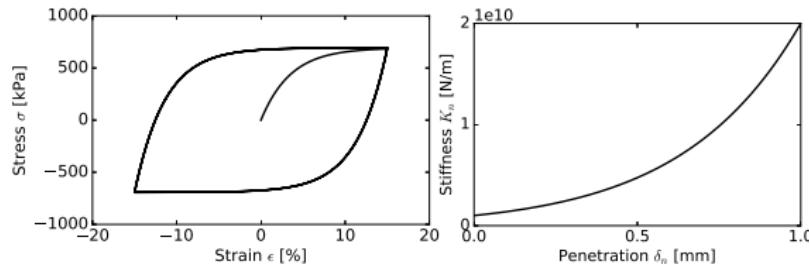
The nuclear power plant structure comprise of

- ▶ Auxiliary building, $f_1^{aux} = 8\text{Hz}$
- ▶ Containment/Shield building, $f_1^{cont} = 4\text{Hz}$
- ▶ Concrete raft foundation: 3.5m thick



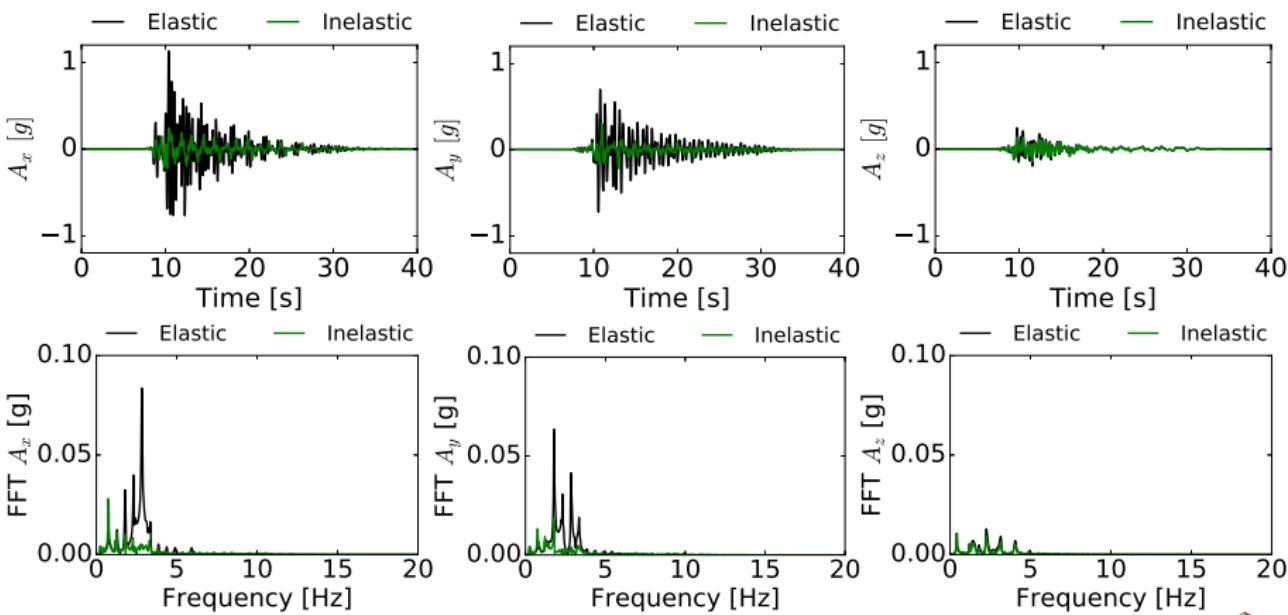
Inelastic Soil and Inelastic Contact

- ▶ Shear velocity of soil $V_s = 500\text{m/s}$
- ▶ Undrained shear strength (Dickenson 1994)
$$V_s[\text{m/s}] = 23(S_u[\text{kPa}])^{0.475}$$
- ▶ For $V_s = 500\text{m/s}$ Undrained Strength $S_u = 650\text{kPa}$ and Young's Modulus of $E = 1.3\text{GPa}$
- ▶ von Mises, Armstrong Frederick kinematic hardening ($S_u = 650\text{kPa}$ at $\gamma = 0.01\%$; $h_a = 30\text{MPa}$, $c_r = 25$)
- ▶ Soft contact (concrete-soil), gaping and nonlinear shear



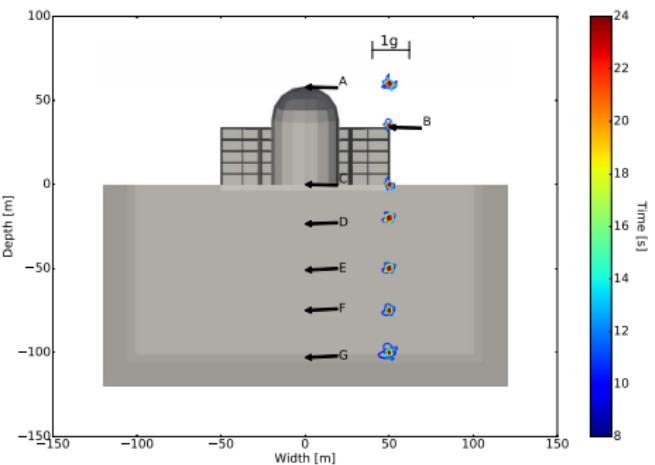
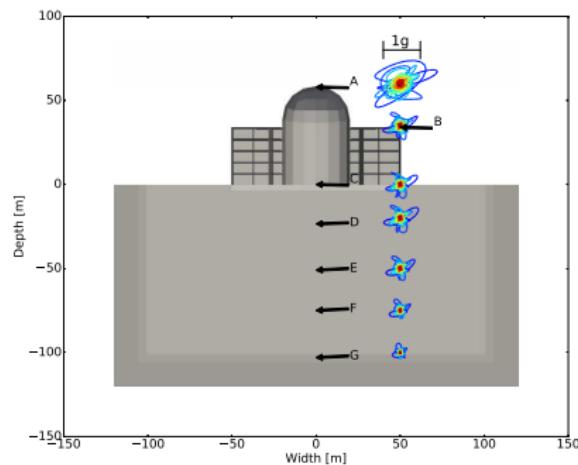
Energy Dissipation

Acc. Response, Top of Containment Building

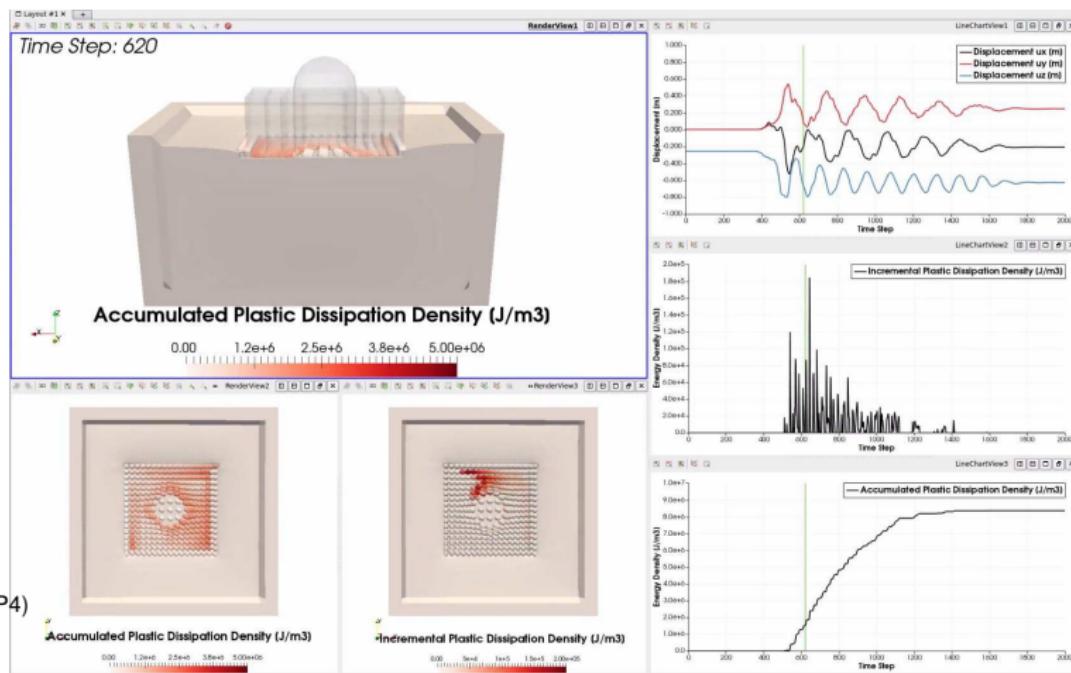


Energy Dissipation

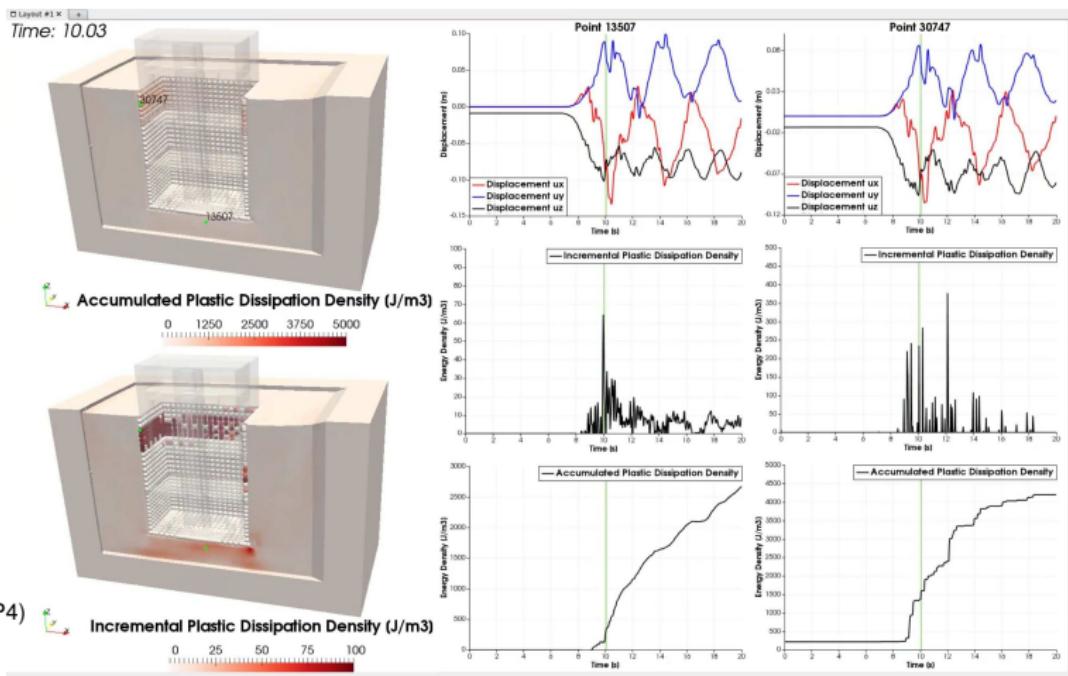
Acceleration Traces, Elastic vs Inelastic



Energy Dissipation in Large-Scale Model (NPP)



Energy Dissipation for a SMR



Introduction
○○○○○○
○○○

Seismic Motions
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○○○○○○○○

Inelasticity
○○○○○○○○○○○○○○○○
●○○○○○○○○

Conclusion
○

Coupled Systems

Outline

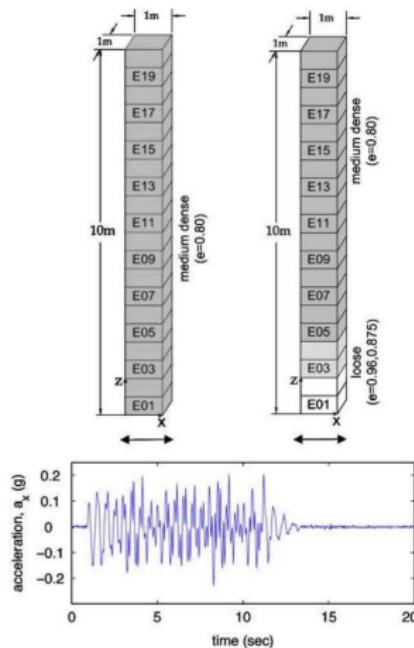
Introduction
Motivation
MS-ESSI Simulator System

Seismic Motions
Regional Models
Stress Test Motions

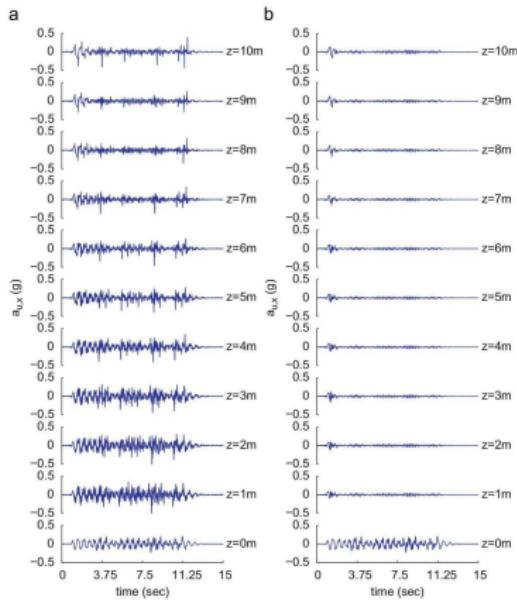
Inelasticity
Energy Dissipation
Coupled Systems

Conclusion

Liquefaction as Base Isolation, Model

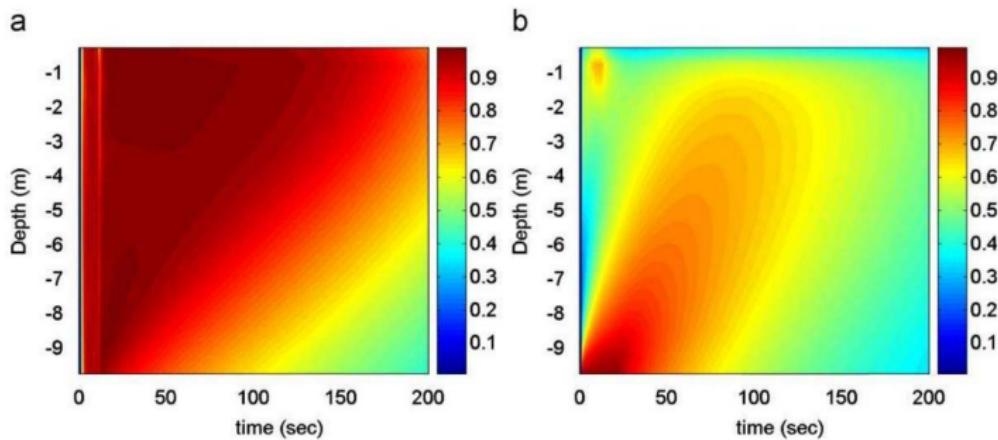


Liquefaction, Wave Propagation

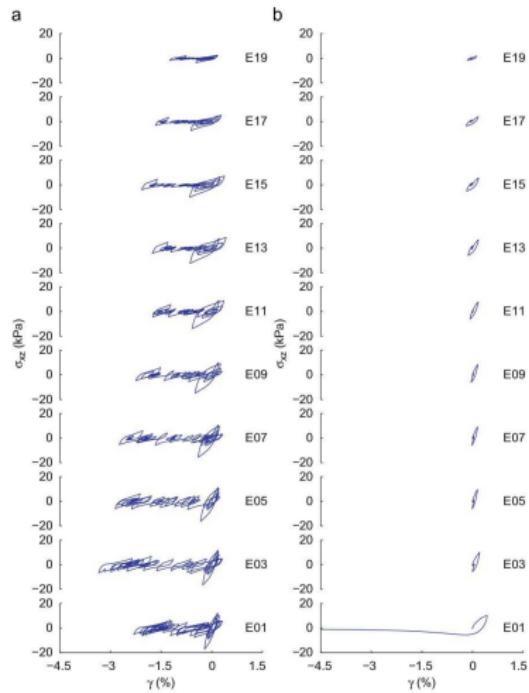


Coupled Systems

Liquefaction, Excess Pore Pressure Ratio

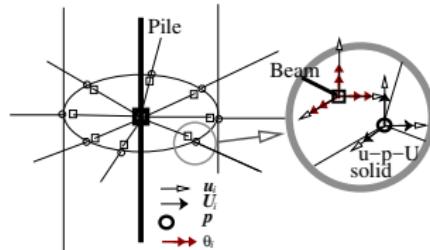
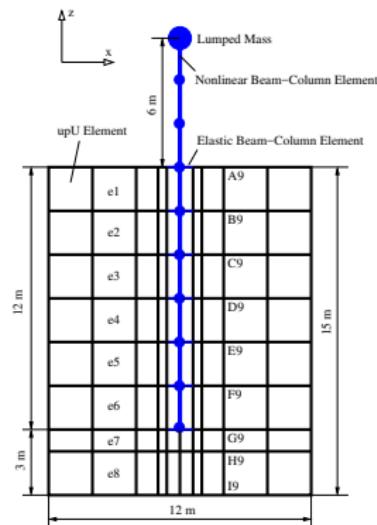
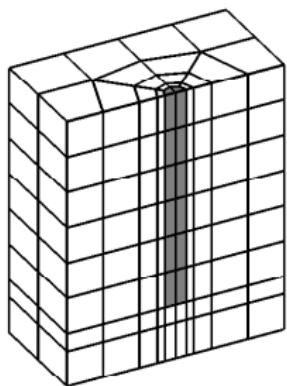


Liquefaction, Stress-Strain Response



Coupled Systems

Pile in Liquefiable Soil, Model



Introduction



Seismic Motions



Inelasticity

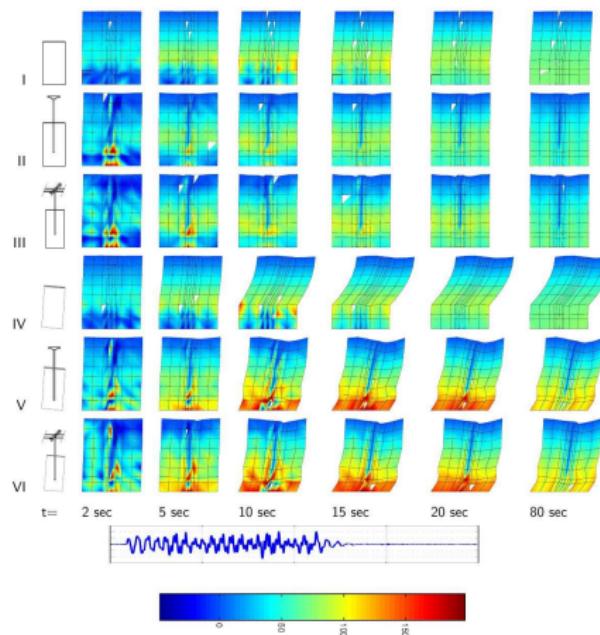


Conclusion



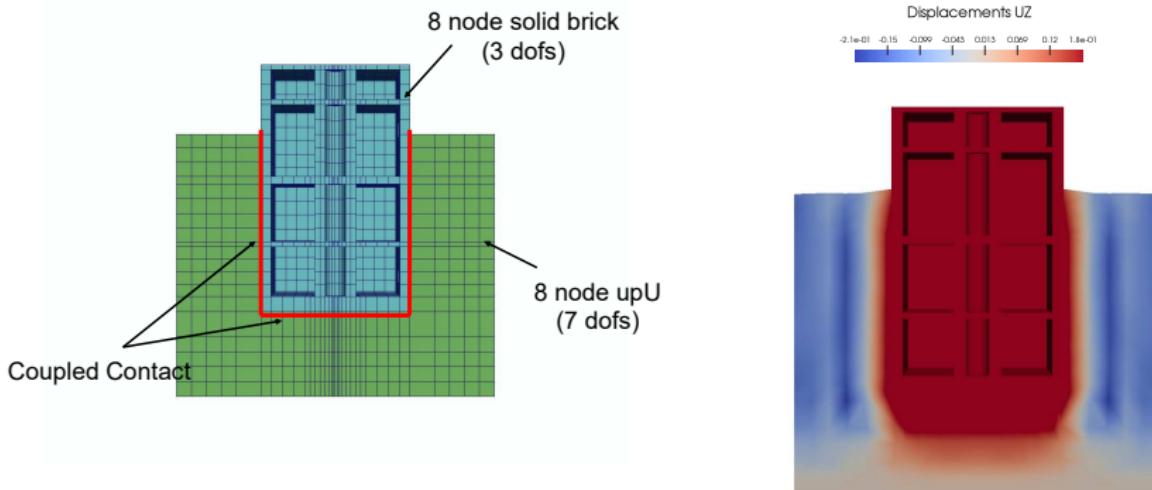
Coupled Systems

Pile in Liquefiable Soil, Results



Coupled Systems

Buoyant Force Simulation



Coupled Systems

Solid/Structure-Fluid Interaction: gmFoam

Mesh separation

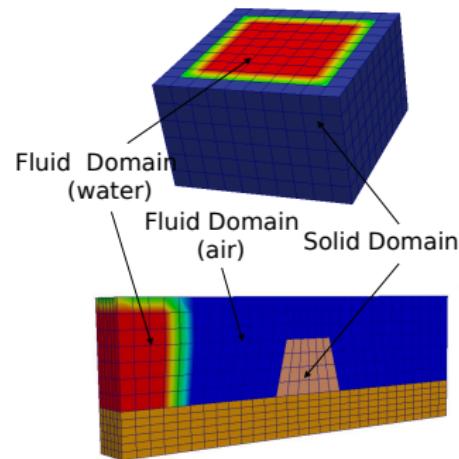
- integrated geometry model
- FEM & FVM mesh conversion
- handle discontinuous mesh

Incorporate gmESSI

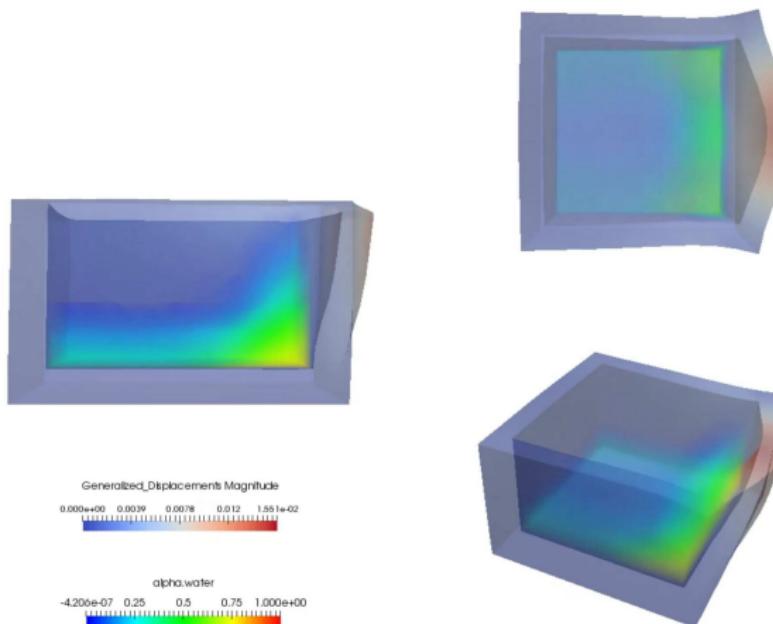
Interface geometry extraction

Interface class **SSFI** in MS-ESSI

MS-ESSI \iff SSFI \iff
OpenFoam



Solid/Structure-Fluid Interaction, Example



Summary

- ▶ Numerical modeling to predict and inform, rather than fit
- ▶ Sophisticated inelastic/nonlinear modeling and simulations need to be done carefully and in phases
- ▶ Education and Training is the key!
- ▶ Collaborators: Feng, Han, Behbehani, Sinha, Wang, Pisanó, Abell, McCallen, McKenna, Petrone, Rodgers, Petersson, Pitarka
- ▶ Funding from and collaboration with the US-DOE, US-NRC, US-NSF, CNSC-CCSN, UN-IAEA, and Shimizu Corp. is greatly appreciated,
- ▶ <http://ms-essi.info/>