

High Performance, High Fidelity Modeling and Simulation of Earthquake-Soil-Structure Interaction for Nuclear Power Industry

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Outline

Introduction

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NRC ESSI Simulator

Software and Hardware Components

Methodology

Case Studies

Case Studies

Earthquakes and Shake-Out

Summary and Conclusions



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The Problem: ESSI Modeling

- ▶ Seismic waves: 6D (3 translations, 3 rotations), Inclined, Body (P and S) and Surface (Love and Rayleigh) waves, Uncorrelated (incoherent), frequency range (0.1Hz – 50Hz)
- ▶ Material behavior (soil, rock, concrete, metal, seismic isolation elements, foundation interface zones...): elastic, elastic-plastic, elastic-damage-plastic
- ▶ Geometries: solids, structures, components and interfaces



ESSI Modeling and Simulation Requirements

- ▶ High fidelity modeling and high performance simulation
- ▶ Reduction of modeling uncertainty
- ▶ High performance (parallel) computing
- ▶ Nonlinear, time domain finite element modeling and simulation of Earthquake – Soil/Rock – Structure Interaction (ESSI) of Nuclear Power Plants (NPPs)
- ▶ Quality Assurance (QA): Verification and Validation
- ▶ Education: seminars, lecture notes, advising
- ▶ Documentation: theory, formulation, implementation, Application Programming Interface (API), verification and validation examples, case studies



ESSI Modeling and Simulation Goals

- ▶ Develop modeling and simulation system for high fidelity modeling and high performance simulation of ESSI for NPPs
 - ▶ Software (GPL, LPGL)
 - ▶ Hardware (off the shelf, customized architecture)
 - ▶ Education (most important)
 - ▶ Documentation (extensive, CC license)
- ▶ The NRC ESSI Simulator
- ▶ The NRC ESSI Simulator is developed for US-NRC, however, it is in public domain



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NRC ESSI Simulator Program

- ▶ Based on a Collection of Useful Libraries
- ▶ Public Domain License (GPL, LGPL)
- ▶ Verification: code, methods and models
- ▶ Validation, uncertainties
- ▶ Documentation: theory, formulation, verification, validation, examples, Application Programming Interface (API), Creative Commons (CC)
- ▶ Education, ensures continuation



NRC ESSI Simulator Program: Library Centric Design

- ▶ Finite element libraries: solids (8, 20, 27, variable # of nodes), beams (displacement based), shell, contact/interface, seismic isolator, single phase (dry), two/three phase (fully/partially saturated, fully coupled)
- ▶ Material model libraries: elastic (isotropic, anisotropic, linear, nonlinear), elastic-plastic (various for soil/rock/concrete/metal)
- ▶ Plastic Domain Decomposition (PDD) for Parallel Computing
- ▶ MOSS library: Modified OpenSees Services (MOSS): changed (for PDD), trimmed, reorganized, API-ed



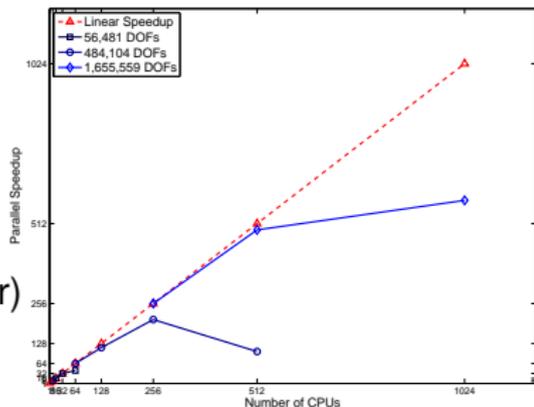
NRC ESSI Simulator Program: Library Centric Design

- ▶ Numerical utility libraries (BLAS, lapack, nDarray, L-Tensor...)
- ▶ Solver libraries (UMFPACK, PETSc,...)
- ▶ Graph libraries (ParMETIS, ZOLTAN)
- ▶ Template meta-programming
- ▶ Domain Specific Language (DSL) library
- ▶ Management: API, V&V, regression testing, documentation, (L)GPL, subversion for code management (number of developers and users)



Plastic Domain Decomposition Method

- ▶ Dynamic computational load (re-)balancing based on
 - ▶ Computer node(s) performance
 - ▶ Network(s) performance
- ▶ Optimally efficient on variable capability computer nodes and multiple interconnect networks:
 - ▶ Tightly connected HPC parallel machines (DMP)
 - ▶ Multiple CPUs / multiple core HPC machines (SMP)
 - ▶ Tightly connected cluster (DMP) of clusters (SMP) (NRC ESSI Simulator Computer)
 - ▶ Loosely connected collection of virtual machines (cloud)



NRC ESSI Simulator Computer

- ▶ Dual network (MPI and PFS) cluster of compute nodes (Distributed Memory Parallel, DMP)
- ▶ Each compute node consists of multiple CPUs/cores (Shared Memory Parallel, SMP, but used as DMP)
- ▶ Use of General Purpose Graphical Processor Units (GPGPU)
- ▶ High availability (I'm root)
- ▶ Secure (US-NRC...)
- ▶ Locally designed and maintained (exportable)
- ▶ Documentation (hardware, system software, system libraries) (internal UCD, US-NRC and external use)



Development Process Management

- ▶ Program libraries peer reviewed,
- ▶ Documentation (extensive), verification and validation examples required
- ▶ Application Program Interface (API)
- ▶ Focus on US-NRC and UCD contributions and needs
- ▶ Public domain libraries source code, documents (GPL, LGPL and CC)



Development Process: Verification

Verification provides evidence that the model is solved correctly.

- ▶ Elements (tests: patch, aspect ratio, ...)
- ▶ Constitutive simulations (integration error, bounds test, localization condition, ...)
- ▶ Finite element level static and dynamic solution advancement (integration) algorithms (analytic solution tests, ...)
- ▶ System of equations solvers (error, ...)
- ▶ Wave propagation (seismic motion input and radiation, energy dissipation, flat frequency modification, ...)



Development Process: Validation

Validation provides evidence that the correct model is solved.

- ▶ Component validation (material modeling, vibration analysis, soil pressures, ...)
 - ▶ Constitutive (material) behavior
 - ▶ Component dynamics
 - ▶ Contact/interface behavior
 - ▶ Energy dissipation characteristics
- ▶ Complete system validation
 - ▶ Lotung LSST tests
 - ▶ Kashiwazaki-Kariwa NPP data (IAEA KARISMA project)
 - ▶ Fukushima-Daiichi NPP data
 - ▶ NEES data (?)



Education and Documentation

- ▶ Lecture Notes
 - ▶ Theory and formulation
 - ▶ Implementation (iterate programming, API)
 - ▶ Application Programming Interface
 - ▶ Verification examples
 - ▶ Validation examples
 - ▶ Practical examples
- ▶ Seminars (US-NRC, IAEA, Nuclear Industry...)



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Real(istic) Seismic Waves and NPP Response

- ▶ Surface (Love and Rayleigh) and body waves (P and S) (six dimensional, 6D, 3 translations, 3 rotations)
- ▶ Lack of correlation modeling (incoherence)
- ▶ Inclined wave field(s)
- ▶ Influence of soil/rock variability and uncertainty on seismic motions



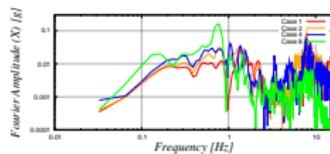
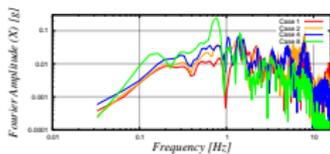
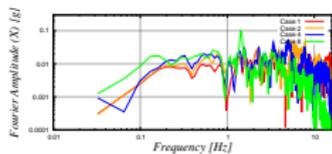
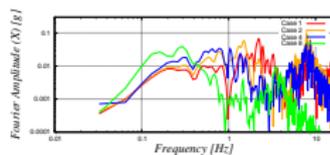
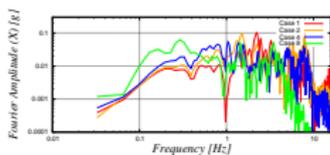
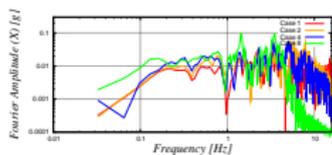
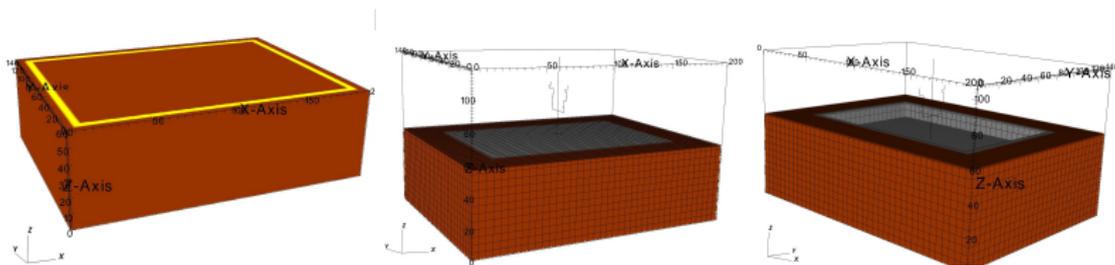
Inelastic Foundation-Soil/Rock Interface

- ▶ Soil/rock – foundation interface slip behavior
- ▶ Changes in ESSI: reduction/increase in demand
- ▶ Dissipation of seismic energy in a slip zone
- ▶ Passive (and active) base isolation



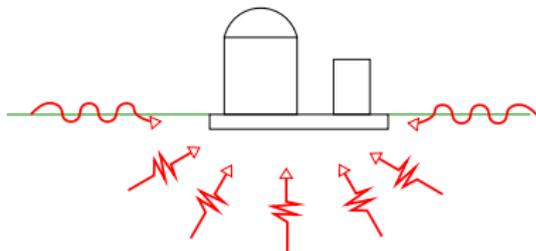
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Early Examples

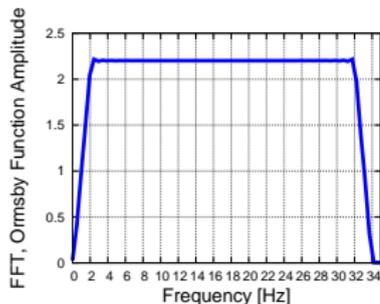
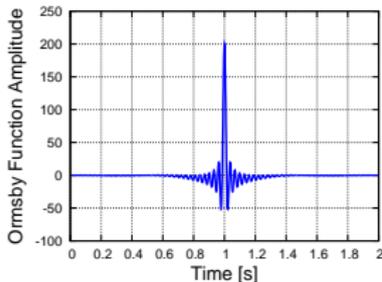


Shake Out: Stress Test NPP Soil-Structure System

- ▶ Synthetic ground motions: emphasize soil-structure system weakness



- ▶ Variations in input angle, input orientation, input energy...



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Summary and Conclusions

- ▶ Importance of reducing modeling uncertainty
- ▶ High fidelity modeling and high performance simulations
- ▶ Education and Documentation crucial (UCD, US-NRC, IAEA, Nuclear Industry,...)
- ▶ Significant number of very interesting technical issues with NPPs for research. licensing and professional practice



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